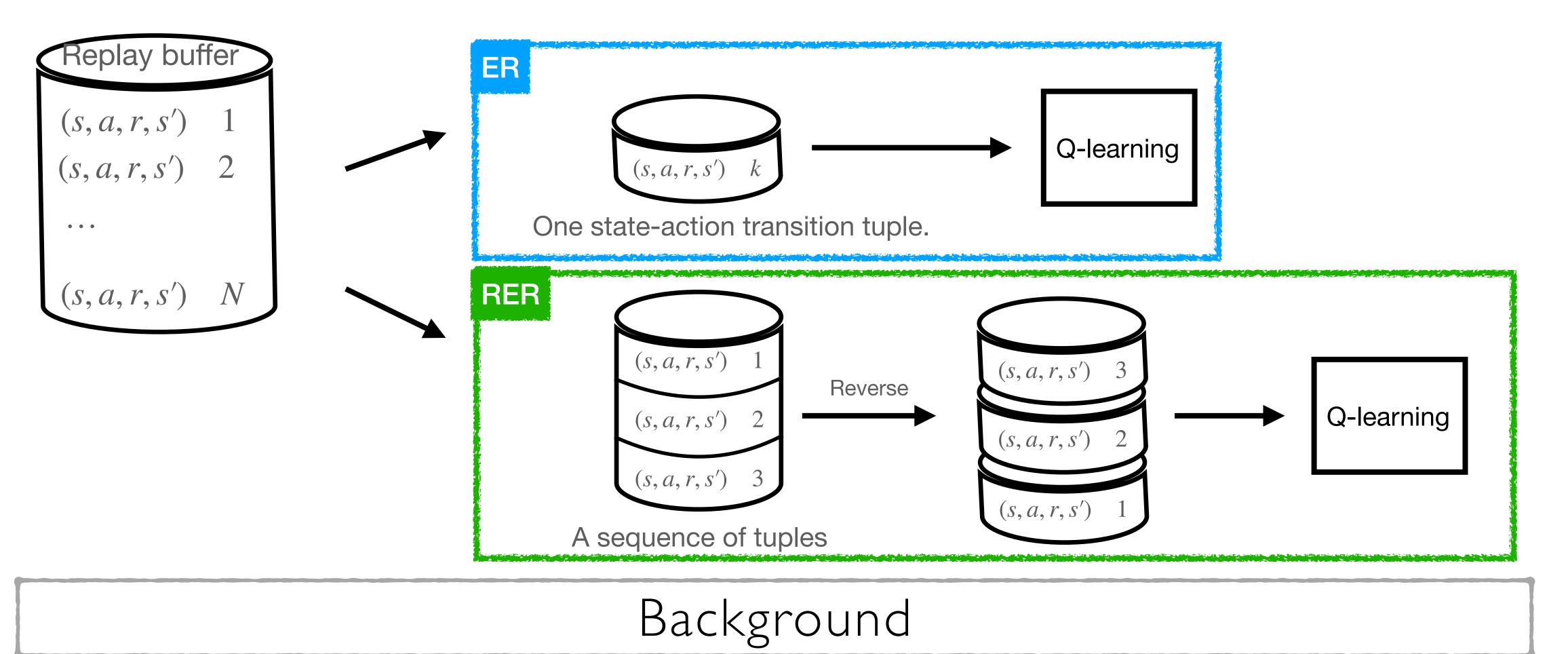


## Introduction

**Experience Replay (ER)** An agent stores past experiences and randomly samples (replays) transitions during the Q-learning process. Many variants, like Prioritized Experience Replay, and Hindsight Experience Replay **Reverse Experience Replay (RER)** Inspired by sequential replay occurs in the rat hippocampus [1] — a region of the brain crucial for memory formation.

**Reverse Experience Replay - based Q-learning** Samples consecutive sequences of transitions (of length L) from the replay buffer. Q-learning updates are performed in the reverse order of the sampled sequences.



Linear MDP Assumption: (1) Reward function: can be written as the inner product of the parameter  $w \in \mathbb{R}^d$ and the feature function

 $\phi(s,a): \mathcal{S} \times \mathcal{S}$ (2) Transition probability: proportional to its corresponding  $P(\cdot | s, a) \propto$ 

(3) The Q function is computed as:

 $Q(s, a; w) = \langle \cdot \rangle$ the error of Q function to the error of learned parameter  $\varepsilon(s,a) = \hat{Q}(s,a) - Q^*$ 

The error breaks into two parts (Lemma 3):

 $\hat{w} - w^* = \Gamma_L \left( w_1 - w^* \right)$ 

Bias term

where  $s_1 \xrightarrow{a_1, r_1} s_2 \xrightarrow{a_2, r_2} s_3 \rightarrow \ldots \rightarrow s_L$  is the sampled sequence, and we denote:

$$\Gamma_L = \left(\mathbf{I} - \eta \phi_1 \phi_1^{\mathsf{T}}\right) \left(\mathbf{I} - \eta \phi_2 \phi_2^{\mathsf{T}}\right) \dots \left(\mathbf{I} - \eta \phi_L \phi_L^{\mathsf{T}}\right), \text{ with each } \phi_L = \phi(s_L, a_L)$$

The bias term can reduce to zero if  $\mathbb{E}_{(s,a)\sim\mu} \begin{bmatrix} \Gamma_L^{\mathsf{T}} \Gamma_L \end{bmatrix}$  is bounded (Lemma C.2), i.e., Need to prove:  $\mathbb{E}_{(s,a)\sim\mu} \begin{bmatrix} \Gamma_L^{\mathsf{T}} \Gamma_L \end{bmatrix} \leq A$  proper bound

I. Foster, David J., and Matthew A. Wilson. "Reverse replay of behavioural sequences in hippocampal place cells during the awake state." Nature (2006)

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# Reinforcement A Tighter Convergence Proof of Reverse Experience Replay

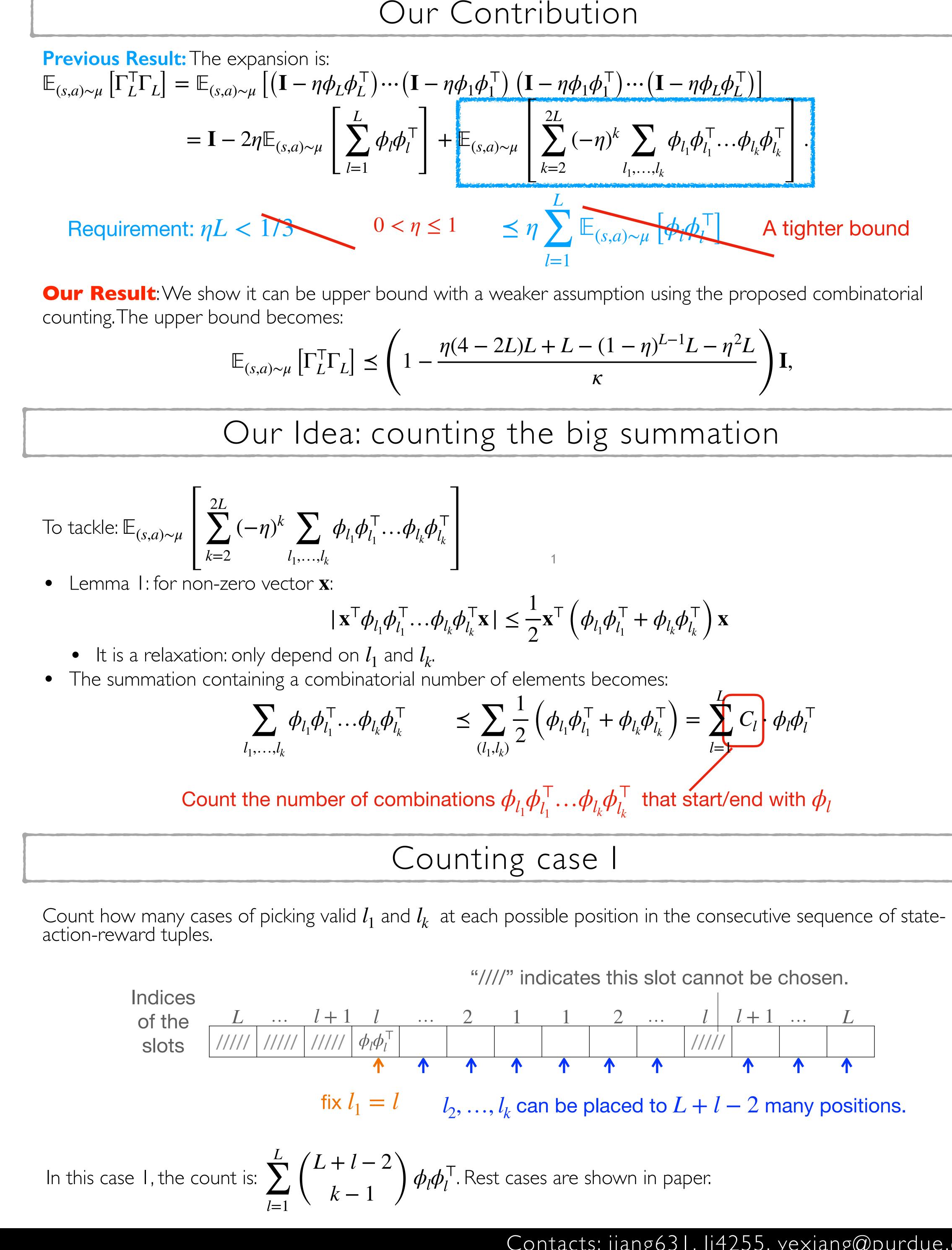
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$$\mathcal{A} \to \mathbb{R}^{d}.$$
  
feature  
 $(s, a)$   
 $(s, a)$   
 $w, \phi(s, a)$   
 $w, \phi(s, a)$   
er  $w$  by Linear MDP:  
 $(s, a) \Leftrightarrow \hat{w} - w^{*}$ 

$$(*)^* + \eta \sum_{l=1}^L \varepsilon_l \Gamma_{l-1} \phi_l$$

variance term





$$\frac{LL + L - (1 - \eta)^{L - 1}L - \eta^2 L}{\kappa} \int \mathbf{I},$$

$$\leq \frac{1}{2} \mathbf{x}^{\mathsf{T}} \left( \phi_{l_1} \phi_{l_1}^{\mathsf{T}} + \phi_{l_k} \phi_{l_k}^{\mathsf{T}} \right) \mathbf{x}$$

$$\frac{1}{2} \left( \phi_{l_1} \phi_{l_1}^{\mathsf{T}} + \phi_{l_k} \phi_{l_k}^{\mathsf{T}} \right) = \sum_{l=1}^{L} C_l \phi_l \phi_l^{\mathsf{T}}$$

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