## PALM: Probabilistic Area Loss Minimization for Protein Sequence Alignment

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[^0]© End-to-End style learning for aligning proteins without the repeated workload.
© The algorithm can do robust learning to reduce the noises in the Biological dataset.
© The developed algorithm can help to find new proteins and drug discovery.

## Pairwise Protein Alignment Problem

Given a sequence pair $(S, T), S=S L A, T=L R P$ and $a=\left[I_{S}, I_{T}, M, I_{T}, I_{S}\right]$.

1. Symbols $M, I_{S}$ and $I_{T}$ : represent a match, an insertion in $S$, and an insertion in $T$, respectively.
2. Alignment $a$ : a sequential symbols $M, I_{S}$ and $I_{T}$.


Figure: Alignment Matrix of sequence pair $(S, T)$.

## Alignment Sequence as Path

Given a sequence pair $(S, T), S=S L A$ and $T=L R P$. $a=\left[I_{S},\right]$

## Insert at S


alignment a

path

Figure: Alignment Matrix of sequence pair ( $S, T$ ).

## Alignment Sequence as Path

Given a sequence pair $(S, T), S=S L A$ and $T=L R P$. $a=\left[I_{S}, I_{T}\right]$

 alignment a

Figure: Alignment Matrix of sequence pair ( $S, T$ ).

## Alignment Sequence as Path

Given a sequence pair $(S, T), S=S L A$ and $T=L R P$. $a=\left[I_{S}, I_{T}, M\right]$

alignment a

path

Figure: Alignment Matrix of sequence pair ( $S, T$ ).

## Alignment Sequence as Path

Given a sequence pair $(S, T), S=S L A$ and $T=L R P$. $a=\left[I_{S}, I_{T}, M, I_{T}\right]$


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## Pairwise Protein Alignment Problem

Given a sequence pair $(S, T), S=S L A, T=L R P$ and $a=\left[I_{S}, I_{T}, M, I_{T}, I_{S}\right]$. We need $\operatorname{Pr}_{\theta}(a \mid S, T)$ : the probability of alignment $a$ with parameter $\theta$.


Figure: Alignment Matrix of sequence pair $(S, T)$.

## Our main tasks

© Learning. Given a training set $\left\{S, T, a^{*}\right\}$, we learn

$$
\max _{\theta} P r_{\theta}\left(a^{*} \mid S, T\right)
$$

© Inference. Given two new sequence $S^{\prime}, T^{\prime}$, predict the most likely alignment $\hat{a}$ :

$$
\hat{a}=\arg \max _{a \in A} \operatorname{Pr}\left(a \mid S^{\prime}, T^{\prime}\right)
$$

## Our Observations

© Biology datasets contain notable errors and alignment offsets from the real experiments.
© Existing approaches are not robust. Because they minimize of the pointwise differences of the two alignments.
© We consider a metric over the area of two alignments.

## Example for falling of pointwise loss

$$
\begin{aligned}
& \text { origin L R P }
\end{aligned}
$$

$$
\begin{aligned}
& \mathcal{L}_{\text {pooint }}\left({\text { gt, } \left.\text { pred }_{1}\right)}\right)=4 / 5
\end{aligned}
$$

Figure: Point-wise loss between ground-truth and pred $_{1}$.

$$
\begin{aligned}
& \text { origin L } \quad \mathrm{P} \quad \mathrm{P}
\end{aligned}
$$

$$
\begin{aligned}
& \mathcal{L}_{\text {point }}\left(\text { gt, } \text { pred }_{2}\right)=4 / 5
\end{aligned}
$$

Figure: Point-wise loss between ground-truth and $\operatorname{pred}_{2}$.

## Example for area loss

$$
\begin{aligned}
& \text { origin L R P } \\
& \begin{array}{cccccccc}
\text { gt } & \mathrm{S}: & \mathrm{S} & - & \mathrm{L} & \overline{\mathrm{P}} & \mathrm{~A} & \mathrm{~S} \\
& \mathrm{~T}: & - & \mathrm{L} & \mathrm{R} & \\
\text { pred }_{1} & \mathrm{~S}: & \mathrm{S} & \mathrm{~L} & - & \mathrm{A} & & \\
& \mathrm{~T}: & - & \mathrm{L} & \mathrm{R} & \mathrm{P} & &
\end{array} \\
& \mathcal{L}_{\text {area }}\left(g t, \text { pred }_{1}\right)=3 / 2
\end{aligned}
$$

Figure: Area loss between ground-truth and pred ${ }_{1}$.

## Example for area loss

$$
\begin{aligned}
& \text { origin L } \quad R \quad P
\end{aligned}
$$

Figure: Area loss between ground-truth and pred $_{2}$.

## Probabilistic Area Distance via MRF I

Our original goal is to :

$$
\max _{\theta} P r_{\theta}\left(a^{*} \mid S, T\right)
$$

With the integration of area loss, we extend to:

$$
\begin{equation*}
\max \operatorname{Pr}\left(a^{*} \mid S, T\right)=\max \sum_{a} \operatorname{Pr} r_{a r e a}\left(a^{*} \mid a, S, T\right) \operatorname{Pr} r_{\theta}(a \mid S, T) . \tag{1}
\end{equation*}
$$

which sums over the latent variable $a$.
© Learning efficiency concern: sums over latent alignments $a \in \mathscr{A}$ is exponential complex;

We use the lower bound

$$
\begin{align*}
\hat{a} & =\arg \max _{a \in A} \operatorname{Pr} r_{\text {area }}\left(a^{*} \mid a, S, T\right) \operatorname{Pr} r_{\theta}(a \mid S, T)  \tag{2}\\
\operatorname{Pr}_{L B}\left(a^{*} \mid S, T\right) & \approx \operatorname{Pr}_{\text {area }}\left(a^{*} \mid \hat{a}, S, T\right) \operatorname{Pr}_{\theta}(\hat{a} \mid S, T) . \tag{3}
\end{align*}
$$

because of the principle of log-sum-exp function: summation usually dominated by one alignment.

## Overview

Training:

1. get sample $\{S, T, a\}$.
2. compute $\operatorname{Pr}_{L B}\left(a^{*} \mid S, T\right)$.
3. sample alignments for computing gradients (see details in paper).
4. repeat 1-3 training until converge.

Testing:

1. given $S^{\prime}, T^{\prime}$, predict $\hat{a}$ by:

$$
\arg \max _{a \in \mathscr{A}} \operatorname{Pr}\left(a \mid S^{\prime}, T^{\prime}\right)
$$

## Precision, Recall and F1-Score Benchmark

1. Sequence $S$ length is between $[1,100]$; Sequence $T$ length is between $[100,200]$;
2. "exact": only an exactly matched alignment is used for computing the true positive rate.

|  | $\|S\| \in[1,100],\|T\| \in[100,200]$ |  |  |
| :--- | :---: | :---: | :---: |
|  | Precision (\%) | Recall (\%) | F1-Score (\%) |
|  | exact | exact | exact |
| DP | 7.8 | 20.4 | 11.3 |
| PALM | $\mathbf{9 . 9}$ | $\mathbf{2 3 . 5}$ | $\mathbf{1 3 . 9}$ |

Table: PALM gets better results especially on longer sequences and remote homologies than the competing approach.

## Precision, Recall and F1-Score Benchmark

1. "4-offset" scenario is a relaxed measure that 4-position off the exact match is allowed.
2. "10-offset" case is relaxed measure with 10-position off.

|  | $\|S\| \in[1,100],\|T\| \in[100,200]$ |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: | :---: |
|  | Precision (\%) | Recall (\%) | F1-Score (\%) |  |  |
|  | exact 4off 10off | exact 4off 10off | exact 4off 10off |  |  |
| DP | $7.8 \mathbf{3 1 . 3}$ | $\mathbf{5 1 . 2}$ | 20.439 .0 | 56.3 | 11.3 |
| PALM | $\mathbf{9 . 9}$ | 29.8 | 48.7 | $\mathbf{2 3 . 5}$ | $\mathbf{4 3 . 1} \mathbf{6 2 . 3}$ |

Table: PALM gets better results on related measurements with " 4 -offset" and " 10 -offset".

## Precision, Recall and F1-Score Benchmark



Table: PALM result for two testing sets with different lengths.

## Conclusion

© We propose robust method for reducing the biological errors and offsets for Protein Alignment.
© We derive efficient dynamic sampling algorithm for model training.
© We demonstrate superior performance against competing approach over Precision/Recall/F1-score.

## Q \& A


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